## Inverse Mapping Theorem

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**Theorem 1** (Inverse Mapping Theorem). Let  $f: U \subset \mathbf{E} \to \mathbf{E}$  be  $C^1$ . Assume that  $x_0 \in U$  is such that  $Df(x_0)$  is invertible. Then there is an open subset V of U containing the point  $x_0$ with the following properties:

i) on V the map is one-one

ii) the image  $f(V)$  is open neighborhood of  $f(x_0)$ 

iii)  $f^{-1}$  is  $C^1$  on  $f(V)$  with  $Df^{-1}(y) = Df(f^{-1}(y))^{-1}$  for all  $y \in V$ .

Before proving this, we recall the mean value inequality in the following form:

**Theorem 2** (Mean Value Inequality-2). Let  $f: U \subset \mathbf{E} \to \mathbf{F}$  be differentiable on the open set U. Let  $x, y \in U$  such that  $[x, y] \subset U$ . Let  $T \in BL(\mathbf{E}, \mathbf{F})$ . Then we have

$$
|| f(y) - f(x) - T(y - x) || \le ||y - x|| \sup_{0 < t < 1} ||Df(x + t(y - x)) - T||.
$$
 (1)

*Proof.* Consider  $\varphi(x) = f(x) - Tx$  and apply the standard mean value inequality to  $\varphi$ .  $\Box$ 

*Proof.* (of IMT) We may assume that  $Df(x_0) = I_{\mathbf{E}}$ , the identity map of **E**. (Justify.)

Since  $Df$  is continuous at  $x_0$  there exists a  $\delta > 0$  such that

$$
||Df(x) - Df(x_0)|| < 1/2, \qquad \text{for all } x \in B(x_0, \delta).
$$
 (2)

For  $x_1, x_2 \in B(x_0, \delta)$  we have by the mean value inequality

$$
|| f(x_1) - f(x_2) - Df(x_0)(x_1 - x_2)|| \le ||x_1 - x_2|| \sup_{0 < t < 1} ||Df(x_1 + t(x_2 - x_1)) - Df(x_0)||. \tag{3}
$$

Now  $x_1 + t(x_2 - x_1) - x_0 = (1 - t)(x_1 - x_0) + t(x_2 - x_0)$  so that  $||x_1 + t(x_2 - x_1) - x_0|| \le$  $(1-t)$   $||x_1 - x_0|| + t ||x_2 - x_0|| < \delta$ . Hence, in view of Eq. 2, Eq. 3 becomes

$$
|| f(x_1) - f(x_2) - (x_1 - x_2)|| \le \frac{1}{2} ||x_1 - x_2||.
$$
 (4)

This implies f is 1-1 on  $B(x_0, \delta)$ .

To show that there exists a ball  $B(y_0, \delta')$  contained in the image of  $B(x_0, \delta)$ , we modify the Newton's method. Newton's method can be briefly described as follows: if  $x_0$  is an approximate zero of  $f(x) = 0$  and if f has a non vanishing derivative around this point  $x_0$ then with  $x_{n+1} := x_n - \frac{f(x_n)}{Df(x_n)}$  $\frac{J(x_n)}{Df(x_n)}$ , defined recursively we have  $x_n$  tending to a limit x which is a zero of f. Draw some pictures to see the geometric idea behind this algorithm. We modify this algorithm below.

Suppose  $y \in B(y_0, \delta')$  for some  $\delta' > 0$ . We want to solve for the equation  $f(x) = y$  with  $x \in B(x_0, \delta)$ . We define recursively  $x_k = x_{k-1} + y - f(x_{k-1})$ . We need to check whether  $x_k \in B(x_0, \delta)$ . We have

$$
x_k - x_{k-1} = x_{k-1} - x_{k-2} - (f(x_{k-1}) - f(x_{k-2})).
$$

Taking norm on both sides, using Eq. 4 and induction we get

$$
||x_{k} - x_{k-1}|| \le (1/2) ||x_{k-1} - x_{k-2}|| \le \cdots \le \frac{1}{2^{k-1}} ||x_1 - x_0|| \le 2^{1-k} \delta'.
$$

Hence if we choose  $\delta' = (\delta/2)$ , then we have  $||x_k - x_{k-1}|| \leq 2^{-k}$  $\sum$ ence if we choose  $\delta' = (\delta/2)$ , then we have  $||x_k - x_{k-1}|| \leq 2^{-k}\delta$ . In particular,  $||x_0 - x_k|| \leq k \leq 6$ . This also shows that  $x_k$  is Cauchy. Let  $\lim x_k = x$ . Clearly we have  $f(x) = y$ . For, from the recursive definition of  $x_k$  by taking the limit as  $k \to \infty$  we get  $x = \lim x_k = \lim_k (x_{k-1} + y - f(x_{k-1})) = x + y - f(x).$ 

For  $y \in B(y_0, \delta/2)$  we define  $g(y) := x$  where  $x \in B(x_0, \delta)$ . We want to prove that g is differentiable on  $B(y_0, \delta/2)$  and that  $Dg(y) = Df(x)^{-1}$ . To see this, we let  $g(y) = x$ ,  $g(y + k) = x + h$  so that  $f(x + h) = y + k$ . Then we have

$$
k = f(x + h) - f(x) = Df(x)h + \psi.
$$
 (5)

where  $\lim_{h\to 0} \frac{\psi}{\|h\|} = 0$ . From Eq. 4 it follows that

$$
||k - h|| = ||f(x + h) - f(x) - h|| \le (1/2) ||h||,
$$

so that  $(1/2) ||h|| \le ||k|| \le (3/2) ||h||$ . In view of Eq. 5 we have  $h - Df(x)^{-1}\psi$ . But  $\lim_{k\to 0} \frac{Df(x)^{-1}\psi}{\|k\|} = 0$  since  $2\|h\| \ge \|k\| \ge 2/3\|h\|$  and  $||Df(x)^{-1}|| \le 2$ . Then

$$
\frac{2}{3} \frac{Df(x)^{-1}\psi}{\|h\|} \le \frac{Df(x)^{-1}\psi}{\|k\|} \le 2 \frac{Df(x)^{-1}\psi}{\|h\|}
$$

This proves the result.

We shall explain the geometric meaning of IMT in the finite dimensional case.

Let  $f: \mathbb{R}^{n+1} \to \mathbb{R}$  be  $C^1$ . Assume that 0 lies in the image of f, without loss of generality. In general, the set  $S := f^{-1}(0)$  does not have any nice geometric property. However, if we assume that

 $f'(p) := \text{grad } f(p) \neq 0$  for all  $p \in S$ 

then S "looks locally like a hyperplane". Of course this needs explanation! Given  $p \in S$ , since  $f'(p) \neq 0$ , we assume without loss of generality that  $\frac{\partial f}{\partial x_{n+1}} \neq 0$ . Then consider the map  $\Phi \colon \mathbb{R}^{n+1} \to \mathbb{R}^{n+1}$  given by  $(x_1, \ldots, x_n, x_{n+1}) \mapsto (x_1, \ldots, x_n, f(x))$ . Then  $\Phi'(p)$  has the Jacobian

$$
\begin{pmatrix}\n1 & 0 & \dots & 0 \\
0 & 1 & \dots & 0 \\
\vdots & \vdots & \ddots & \vdots \\
\frac{\partial f}{\partial x_1} & \frac{\partial f}{\partial x_2} & \dots & \frac{\partial f}{\partial x_{n+1}}\n\end{pmatrix}.
$$



The determinant of this matrix is  $\pm \frac{\partial f}{\partial x}$  $\frac{\partial f}{\partial x_{n+1}} \neq 0$  and hence  $\Phi'(p)$  is invertible. Thus  $\Phi$  is a "C<sup>1</sup>diffeomorphism" of an open neighborhood of V of p in  $\mathbb{R}^{n+1}$  onto an open set  $\Phi(V) \subset \mathbb{R}^{n+1}$ , by IMT. (By a  $C^1$ -diffeomorphism we mean a map F which is  $C^1$ , one-one on its domain U and  $F(U)$  is open and  $F^{-1}$  is also  $C^1$  on  $F(U)$ .) Now we introduce a new set of coordinates on V by setting  $y_i(r) := u_i \circ \Phi(r)$ , where  $u_i$  are the 'usual' coordinates on  $\mathbb{R}^{n+1}$ :  $u_i(x) := x_i$ . In plain language this is:

$$
y_i(r) = \begin{cases} r_i & \text{if } 1 \le i \le n \\ f(r) & \text{if } i = n+1. \end{cases}
$$

With respect to this new set of coordinates  $y_i$ , S has a local description around p on  $V \cap S$ : it is the "hyperplane"  $\{y_{n+1} = 0\}$ . Thus by taking a suitable system of coordinates we "straighten" the hypersurface to a hyperplane locally.

To see how this change of coordinates can help us we pose the following question: Suppose the hypersurface S is also described around p as  $g^{-1}(0)$ . That is, there exists an open set  $U \ni p$  such that  $S \cap U = g^{-1}(0)$ , with  $g: U \to \mathbb{R}$  being a  $C^1$ -function. Is g divisible by f at least locally around  $p$ ? That is, does there exist another function h defined in an open set containing p on which we can write  $q = fh$ ?

Let  $F := f \circ \Phi^{-1}$  and  $G := g \circ \Phi^{-1}$ . Then it follows that  $\Phi(V \cap S) = \{y_{n+1} = 0\} \cap \Phi(V)$ . The above question then reduces to an equivalent one: Is G divisible by  $F = y_{n+1}$  locally around 0? This is certainly easy to answer (in the affirmative, by Taylor expansion).

## The moral therefore is that the IMT allows us to use a coordinate system that is most convenient or that simplifies the geometric problem on hand.

Before closing this section we shall state the implicit function theorem and leave its proof to the reader. First recall that if  $f: U \subset \mathbf{E} \times \mathbf{F} \to \mathbf{G}$  is differentiable at  $(x, y)$  then we have

$$
f'(x, y)(u, v) = D_x f(x, y)(u, 0) + D_y f(x, y)(0, v)
$$

where  $D_x f(x, y)$  is the *partial derivative* of f in the first variable etc.

**Theorem 3.** Assume that  $f: U \subset \mathbf{E} \times \mathbf{F} \to \mathbf{G}$  is such that

i)  $f(x_0, y_0) = 0$  for some  $(x_0, y_0) \in U$ 

ii)  $D_u f$  exists on U and  $Df(x_0, y_0) : \mathbf{F} \to \mathbf{G}$  is continuous and bijective

iii) f and  $D_y f$  are continuous at  $(x_0, y_0)$ .

Then there exist  $\rho$  and r such that for all  $x \in B(x_0, \rho)$  there is a unique  $y(x) \in \mathbf{F}$  for which  $||y(x) - y_o|| \leq r$  and  $f(x, y(x)) = 0$ . Furthermore, if f is  $C^1$  for  $0 \leq k \leq \infty$  around  $(x_0, y_0)$ , then so is  $x \mapsto y(x)$  around  $x_0$ .  $\Box$